Learning Multiplex Graph with Inter-layer Coupling

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Motivation



[Source: NETWORK MANAGEMENT]

[Source: Sapien Labs]

- Graphs are natural ways to represent social, biology, transportation, power networks, and others.
- Graph Signal Processing (GSP) extends signal processing to graph data and enables 'interpretable' inference of data.

Motivation



Multilayer protein networks [Source: [Zhao et al., 2016]]

Multilayer social network [Source: [Hanteer and Rossi, 2019]]

- Prior works consider closed systems with single layer of networks, but networks do not live in isolation [Kivelä et al., 2014].
- A general model is multiplex graph a node is present on ≥ 2 layers of graphs, each with different topology e.g., opinion dynamics on ≥ 2 topics, weather measurement stations, brain signals, etc.
- ▶ Note: We focus on *multi-attribute graph signals*.

Goals and Contributions

To extend GSP methods to multiplex graphs: signal analysis, topology learning, etc. — we focus on graph topology learning.

Contributions:

- Multiplex Graph Filter for multi-attribute graph signals with nonlinear intra-/inter-layer couplings.
- Interpret TV/smoothness criterion as a matched filter criterion – extend to handle inter-layer couplings.
- Alternating Optimization Procedure for efficient multiplex graph learning.



Related Works

- Models for multi-way graph signals (on multiplex graphs)
 - [Zhang et al., 2023b] tensor GSP model, but it lacks inter-layer coupling dynamics.
 - [Natali et al., 2020, Grassi et al., 2017] considered product graph signal models which is a special case of multiplex graphs.

Multiplex graph topology learning

- [Kalaitzis et al., 2013] [Kadambari and Chepuri, 2021],
 [Einizade and Sardouie, 2023] learn product graphs using graph signals via smoothness, spectral template, etc.
- Our prior work [Zhang et al., 2023a] consider a fine-grained model for product graph learning.

Graph Machine Learning

- [Cen et al., 2019, Zhang et al., 2019] seek embeddings for graph representation on heterogeneous graph with HetGNN.
- [Butler et al., 2023] proposed a model for convolutional learning on multigraph.
- and many others ...

Multiplex Graph Model

- $G = \langle V, \mathcal{E}, \mathcal{G}^C \rangle$ with nodes V, layer edges \mathcal{E} , coupling graph \mathcal{G}^C .
- There are |V| = N nodes and L layers.
- ► Layer Graphs: For $\ell = 1, ..., L$, \mathcal{G}_{ℓ} with supernodes V_{ℓ} , edges E_{ℓ} , representing intra-layer links with adjacency A_{ℓ} .
- **Coupling Graph:** \mathcal{G}^{C} for inter-layer links with adjacency **C**.
- Adjacency Matrix: Layer-wise $A_L = blkdiag(A_1, ..., A_L)$ and coupling $A_C = C \otimes I_N$. e.g.: supra-adjacency: $A = A_L + A_C$.



Multi-attribute Graph Filter and Signals.

We model multi-attribute graph signal as

$$\boldsymbol{y}^{(m)} = \mathcal{H}(\boldsymbol{\mathcal{A}}_{L}, \boldsymbol{\mathcal{A}}_{C})\boldsymbol{x}^{(m)} + \boldsymbol{w}^{(m)} \in \mathbb{R}^{NL}, \qquad (1)$$

→ H(A_L, A_C) shall model the multiplex with distinct intra-layer and coupling dynamics → a general multi-attribute graph filter model¹:

$$\mathcal{H}(\mathcal{A}_{L},\mathcal{A}_{C}) = \sum_{t=0}^{T-1} \sum_{j=0}^{2^{t}-1} h_{t,j} \prod_{i=1}^{t} \mathcal{A}_{L}^{b_{t,j}^{(i)}} \mathcal{A}_{C}^{1-b_{t,j}^{(i)}}, \quad b_{t,j}^{(i)} \in \{0,1\} \quad (\mathsf{GF})$$

Remark: the tensor GSP model [Zhang et al., 2023b] essentially takes the polynomial filter of supra-adjacency matrix

$$\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C) = \sum_{t=0}^{T-1} h_t (\mathcal{A}_L + \mathcal{A}_C)^t.$$
 (GF-t)

¹Note: this is a multinomial with exponential number of coefficients. Similar observations are made in [Butler et al., 2023].

Expressibility of (GF): Multiplex Graph Dynamics

It is necessary to use the model (GF) with

$$\mathcal{H}(\mathcal{A}_{L},\mathcal{A}_{C}) = \sum_{t=0}^{T-1} \sum_{j=0}^{2^{t}-1} h_{t,j} \prod_{i=1}^{t} \mathcal{A}_{L}^{b_{t,j}^{(i)}} \mathcal{A}_{C}^{1-b_{t,j}^{(i)}}, \quad b_{t,j}^{(i)} \in \{0,1\}$$

Supra-diffusion Process:

E.g., dynamics of epidemics [Kivelä et al., 2014]:

$$\frac{d\mathbf{y}_{\ell}(t)}{dt} = -\mathbf{y}_{\ell}(t) + \underbrace{\mathbf{A}_{\ell}\mathbf{y}_{\ell}(t)}_{\text{intra-layer}} + \underbrace{\sum_{\ell'=1}^{L} C_{\ell,\ell'}\mathbf{y}_{\ell'}(t)}_{\text{inter-layer}} + \mathbf{x}_{\ell}^{(m)}.$$

Steady-state of the diffusion process:

$$\mathbf{y}^{(m)} = \lim_{t \to \infty} \mathbf{y}(t) = (\mathbf{I}_{NL} - (\mathbf{A}_L + \mathbf{A}_C))^{-1} \mathbf{x}^{(m)},$$

Fine with (GF) and (GF-t).

Expressibility of (GF): Multiplex Graph Dynamics

It is necessary to use the model (GF) with

$$\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C) = \sum_{t=0}^{T-1} \sum_{j=0}^{2^t-1} h_{t,j} \prod_{i=1}^t \mathcal{A}_L^{b_{t,j}^{(i)}} \mathcal{A}_C^{1-b_{t,j}^{(i)}}, \quad b_{t,j}^{(i)} \in \{0,1\}$$

Opinion Dynamics:

• Evolution with mutual trust C and logical matrix A_{ℓ} :

$$\mathbf{y}_{\ell}(t+1) = \underbrace{\mathbf{A}_{\ell} \sum_{\ell'=1}^{L} C_{\ell,\ell'} \mathbf{y}_{\ell'}(t)}_{\text{coupled inter- and intra-layer}} + \mathbf{x}_{\ell}^{(m)},$$

Steady-state opinions:

$$oldsymbol{y}^{(m)} = \lim_{t o \infty} oldsymbol{y}(t) = (oldsymbol{I}_{NL} - oldsymbol{\mathcal{A}}_L oldsymbol{\mathcal{A}}_C)^{-1} oldsymbol{x}^{(m)}.$$

Fine with by (GF) **but not** (GF-t).

Multiplex Graph Learning



Task: Given graph signals $\{\mathbf{y}^{(m)}\}_{m=1}^{M}$, estimate multiplex graph \mathcal{A}_L , \mathcal{A}_C .

General idea: Following [Dong et al., 2016], exploit smoothness of multi-attribute graph signals → how to leverage (GF)?

TV Objective and Matched Graph Filter

(Let's take a slight detour ...)

- Let S ∈ ℝ^{N×N} be the pairwise distance matrix of graph signals and we aim at learning the (simple) graph adjacency A.
- ► Consider the **Dirichlet energy criterion** in [Berger et al., 2020]²:

$$TV(\hat{\boldsymbol{A}}) := \sum_{i,j=1}^{N} \hat{A}_{ij} \frac{1}{M} \|\boldsymbol{y}_i - \boldsymbol{y}_j\|^2 = \sum_{i,j=1}^{N} \hat{A}_{ij} S_{ij} = \langle \hat{\boldsymbol{A}} | \boldsymbol{S} \rangle.$$
(2)

With $\mathbf{y}^{(m)} \approx \mathcal{H}(\mathbf{A}) \mathbf{x}^{(m)}$ and under mild condition

$$\min_{\hat{\boldsymbol{A}}} \operatorname{TV}(\hat{\boldsymbol{A}}) \stackrel{approx.}{\Longleftrightarrow} \max_{\hat{\boldsymbol{A}}} \langle \hat{\boldsymbol{A}} \, | \, \mathcal{H}^2(\boldsymbol{A}) \rangle.$$

If H²(A) is a low-pass graph filter [Ramakrishna et al., 2020], then its first order approximation³ is given by H²(A) ≈ A.

Criterion (2) can be interpreted as a matched filter criterion.

³In general $\mathcal{H}(\mathbf{A})$ is not known a-priori, 1st order approx is the best we can do.

 $^{^2 {\}rm Graph}$ learning methods based on quadratic TV such as [Dong et al., 2016] can be interpreted similarly.

Tractable Approximation to (GF)

- ► (GF) is **intractable** in general : exponential no. of parameters.
- Inspired by the examples, consider the approximation⁴:

 $\mathcal{H}(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C})\approx\overline{\mathcal{H}}_{1}(\boldsymbol{\mathcal{A}}_{L})+\overline{\mathcal{H}}_{2}(\boldsymbol{\mathcal{A}}_{C})+\overline{\mathcal{H}}_{3}(\boldsymbol{\mathcal{A}}_{L}\boldsymbol{\mathcal{A}}_{C}+\boldsymbol{\mathcal{A}}_{C}\boldsymbol{\mathcal{A}}_{L}) \quad (\text{a-GF})$



- $\overline{\mathcal{H}}_1, \overline{\mathcal{H}}_2, \overline{\mathcal{H}}_3$ are polynomials.
- ▶ $\overline{\mathcal{H}}_1(\mathcal{A}_L)$, $\overline{\mathcal{H}}_2(\mathcal{A}_C)$ model intra- and inter-layer graph dynamics,
- $\overline{\mathcal{H}}_3$ captures two-hops neighbors and cross-layer interactions.

⁴Also assume that $\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C)\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C)^{\top}$ obeys a similar form.

Matched Graph Filter for Multiplex Graph Learning

• $S \in \mathbb{R}^{NL \times NL}$ = pairwise distance matrix of **multi-attribute** signals.

Consider a generalized Dirichlet energy criterion

$$TV(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}) := \sum_{i,j=1}^{NL} \left[\hat{h}(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}) \right]_{ij} S_{ij} = \langle \hat{h}(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}) \,|\, \boldsymbol{\boldsymbol{S}} \rangle.$$
(3)

▶ With (a-GF), we have

$$\boldsymbol{S} \approx \overline{\mathcal{H}}_1(\boldsymbol{\mathcal{A}}_L) + \overline{\mathcal{H}}_2(\boldsymbol{\mathcal{A}}_C) + \overline{\mathcal{H}}_3(\boldsymbol{\mathcal{A}}_L \boldsymbol{\mathcal{A}}_C + \boldsymbol{\mathcal{A}}_C \boldsymbol{\mathcal{A}}_L).$$

Assumption H1: \$\overline{\mathcal{H}}_1(\cdot)\$, \$\overline{\mathcal{H}}_2(\cdot)\$, \$\overline{\mathcal{H}}_3(\cdot)\$ are low-pass graph filters.
 Under H1, the matched multiplex graph filter design:

$$\hat{h}(\mathcal{A}_L, \mathcal{A}_C) = \mathcal{A}_L + \mathcal{A}_C + \lambda (\mathcal{A}_C \mathcal{A}_L + \mathcal{A}_L \mathcal{A}_C).$$

 \rightarrow A high-order smoothness metric!

Multiplex Graph Learning - Algorithm

Under H1, we formulate the **bi-convex** problem:

$$\min_{\hat{\boldsymbol{\mathcal{A}}}_{L}, \hat{\boldsymbol{\mathcal{A}}}_{C} \in \mathcal{A}} \left\langle \widehat{\boldsymbol{\mathcal{A}}}_{L} + \widehat{\boldsymbol{\mathcal{A}}}_{C} + \lambda \left(\widehat{\boldsymbol{\mathcal{A}}}_{L} \widehat{\boldsymbol{\mathcal{A}}}_{C} + \widehat{\boldsymbol{\mathcal{A}}}_{C} \widehat{\boldsymbol{\mathcal{A}}}_{L} \right) \mid \boldsymbol{S} \right\rangle + \alpha \left(\|\widehat{\boldsymbol{\mathcal{A}}}_{L}\|_{F}^{2} + \|\widehat{\boldsymbol{\mathcal{A}}}_{C}\|_{F}^{2} \right)$$
(4)

- Algorithm: alternating optimization (AO) can be applied:
 Fix Â_C and solve for Â_L → fix Â_L and solve for Â_C → ···
- The AO subproblems are separable and tractable each involves convex problems size of N × N or L × L.
- AO finds a stationary point of (4) as iteration number goes to ∞ [Grippo and Sciandrone, 2000].
- Remark: when λ = 0, the problem reduces into that of [Kadambari and Chepuri, 2021].

Topology Reconstruction under strong coupling



- ► Weak coupling: $\mathcal{H}_{wk}(\mathcal{A}_L, \mathcal{A}_C) = (I \tau_{wk}(\mathcal{A}_L + \mathcal{A}_C))^{-1}$.
- Observation: AUC performance generally improves as M increases/deteriorates as N increases.
- Proposed AO ($\lambda = 0.1$) attains **similar** performance to the benchmark.

Topology Reconstruction under strong coupling



- ► Strong coupling: $\mathcal{H}_{str}(\mathcal{A}_L, \mathcal{A}_C) = (\mathbf{I} \tau_{str} \mathcal{A}_L \mathcal{A}_C)^{-1}$.
- Benchmark fails in estimating graph topologies under strong coupling.
- ▶ Proposed AO (λ = 5) recovers topology effectively regardless of layer coupling robustly.

Summary

Takeaway: Distinct **inter-layer and intra-layer interactions** dynamics require careful modeling for multiplex graph learning.

We have introduced a method for learning multiplex network structures from multi-attribute graph signals:

- General multiplex graph filter to model complex signal interactions.
- ► Matched filter perspective to graph learning by smoothness → a high-order smoothness metric aimed at inter-layer coupling.
- An efficient AO procedure for learning graph topologies.
- Future work: modeling of multiplex graph signals, adopting other GSP tools, ...

Thank you!

Contact me at htwai@cuhk.edu.hk if you are interested.

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